

Parameter Space Abstraction and Unfolding Semantics of Discrete Regulatory Networks

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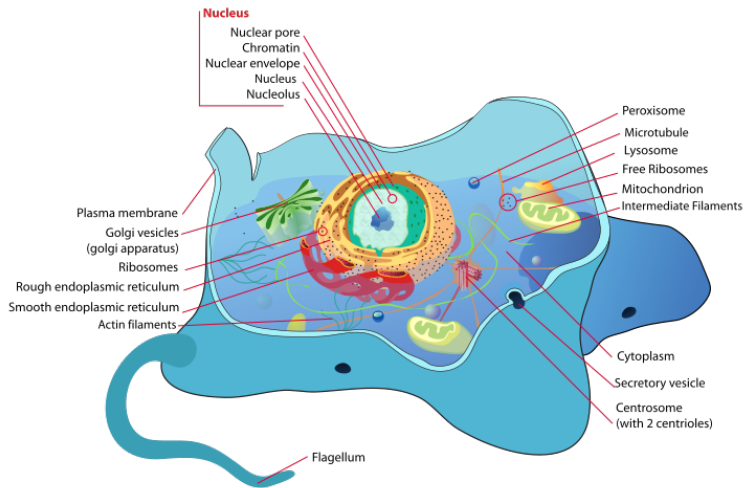
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³LRI UMR 8623, Univ. Paris-Sud – CNRS, Université Paris-Saclay, Orsay, France

MeFoSyLoMa 29/09/2017

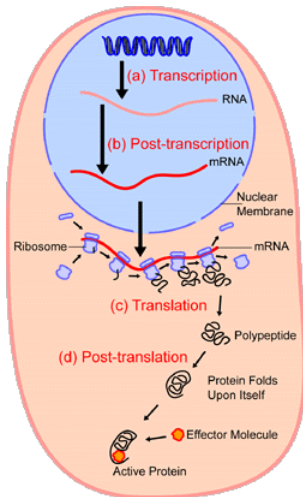
Outline

- ▶ Motivation
- ▶ Parametric Regulatory Networks
- ▶ Abstraction of Parameter Space
- ▶ Unfoldings
- ▶ Experimental results
- ▶ Conclusion



Source: Wikipedia

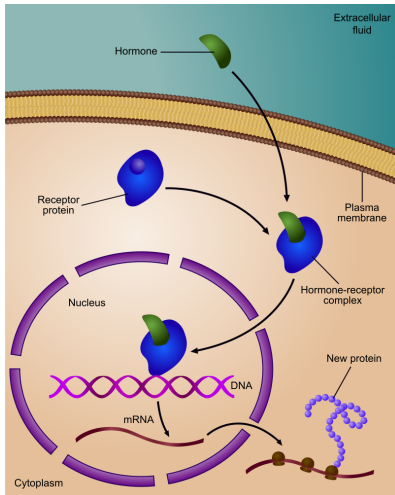
Cell Dynamics are facilitated by synthesis of proteins.



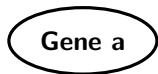
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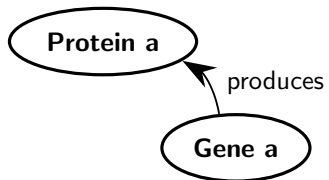
Dynamics Regulation

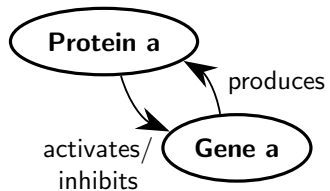
Gene activation is subject to presence of combination of transcription factors, e.g. proteins or complexes.

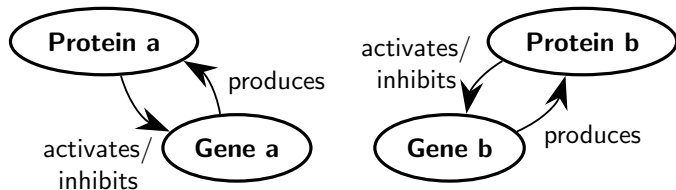


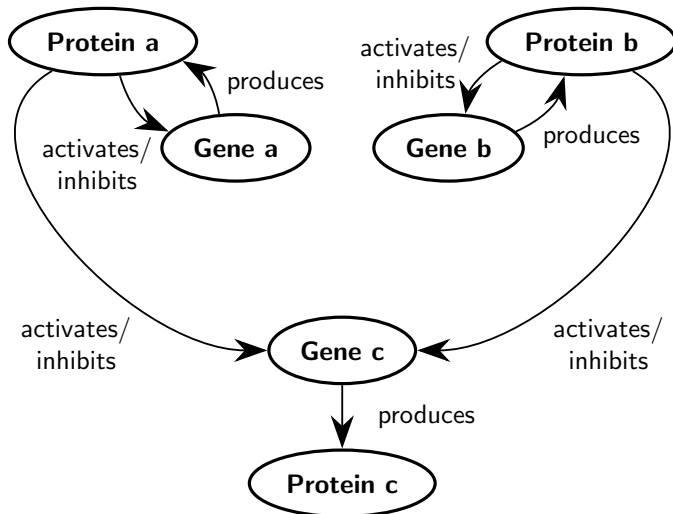
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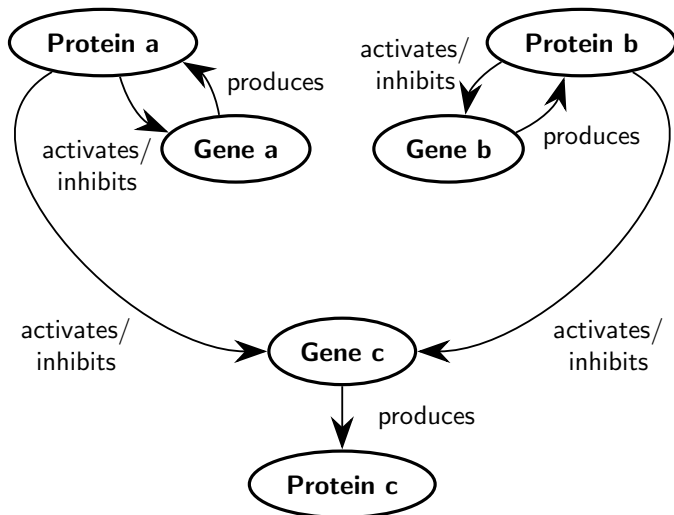




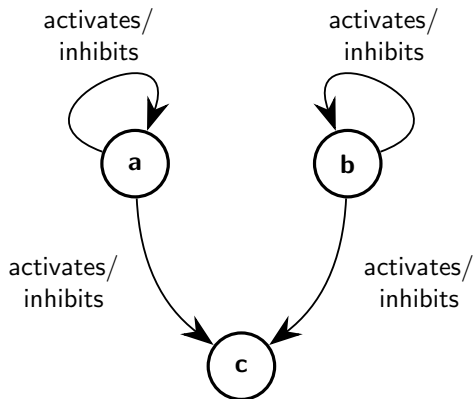






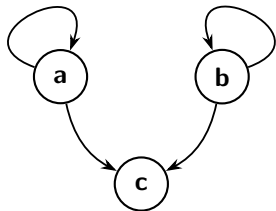


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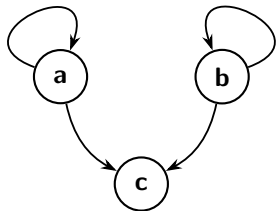
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Influence graph:



Boolean Networks

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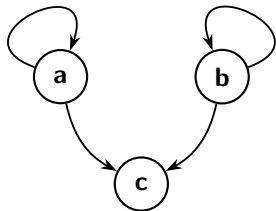


Definition (Boolean Network)

A Boolean network is a set of n Boolean variables $V = \{v_1, \dots, v_n\}$ and a composite function $F = (f_1, \dots, f_n) : \{0, 1\}^V \rightarrow \{0, 1\}^V$.

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$$f_a \equiv \neg a$$

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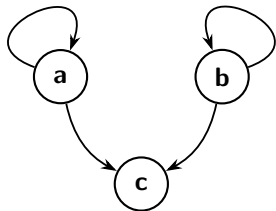
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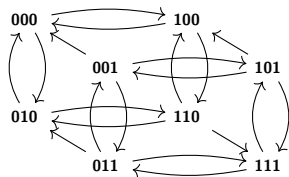
Semantics:

Synchronous (values of all nodes update at the same time):

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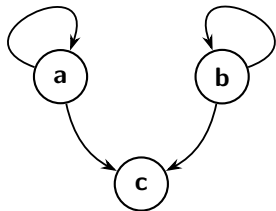


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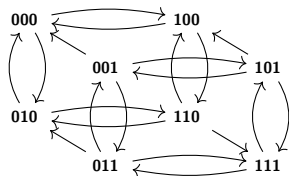
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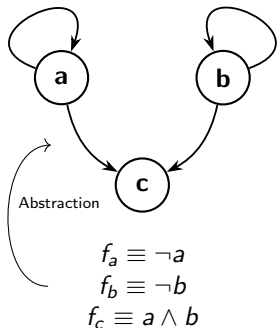


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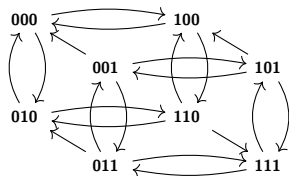
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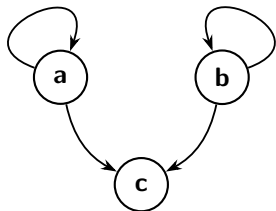


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Parametric Regulatory Networks

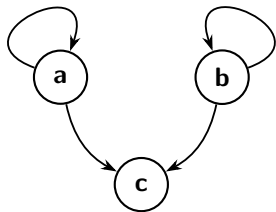
Influence graph:



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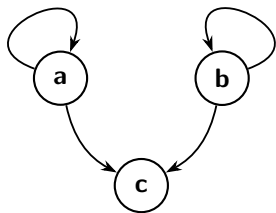
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A parametric regulatory network is an influence graph $G = (V, I)$ where $V = \{v_1, \dots, v_n\}$ is a set of Boolean variables and $I \subseteq V \times V$.

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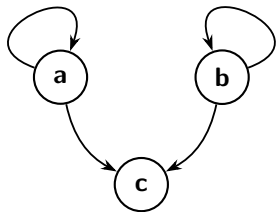
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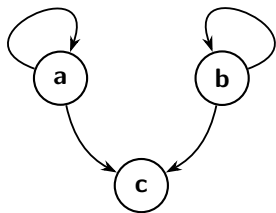
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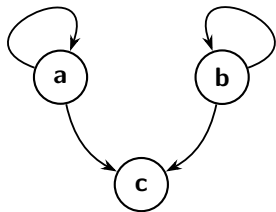
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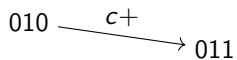
Exploring PRN Dynamics

We construct a possible trace (run) of the model from a given initial state:

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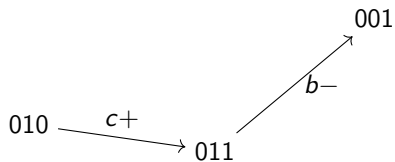
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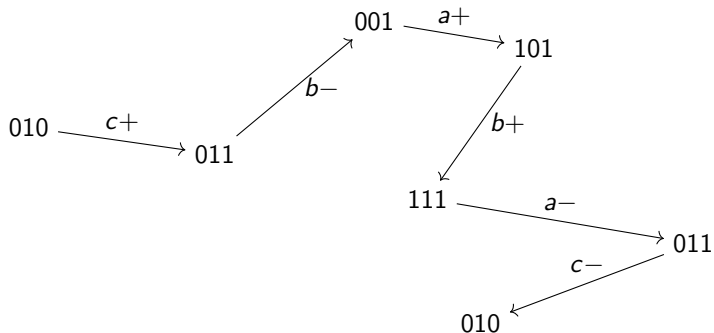
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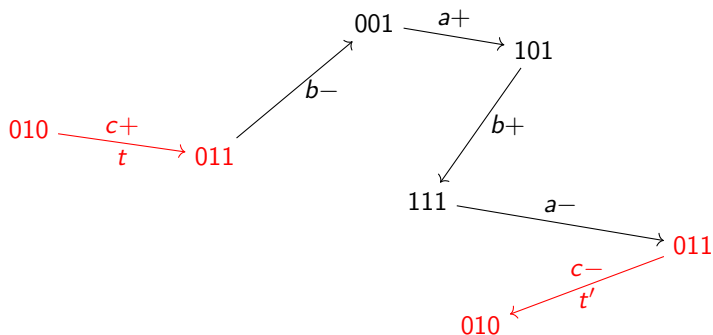
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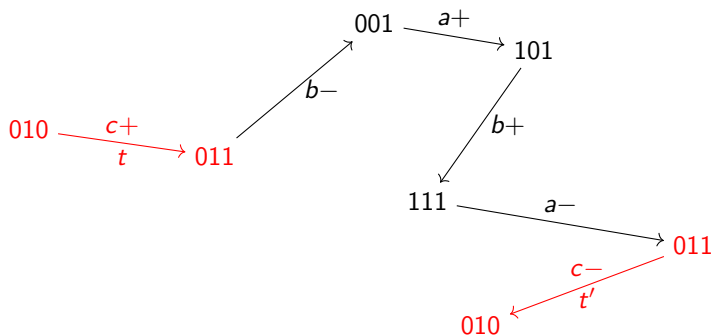


$$\mathcal{P}_t = \{P \in \mathbb{P} \mid P_{c,01} = 1\}$$

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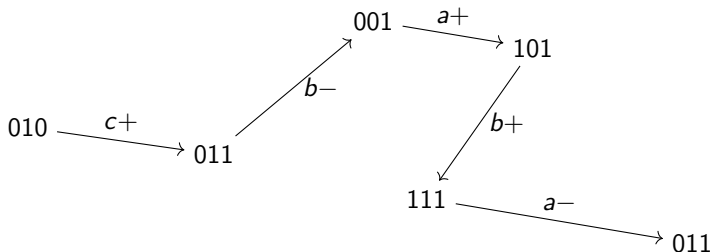
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We keep track of a set of viable parametrisations $p(T)$ for a given set of transitions T .

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The number of parametrisations is double exponential in the number of regulators.

Parametrisation Sets

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Bounded convex sublattice is given uniquely by its lower and upper bound.

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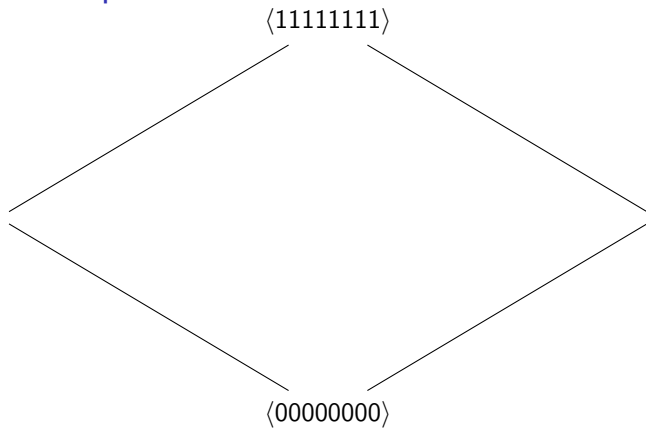
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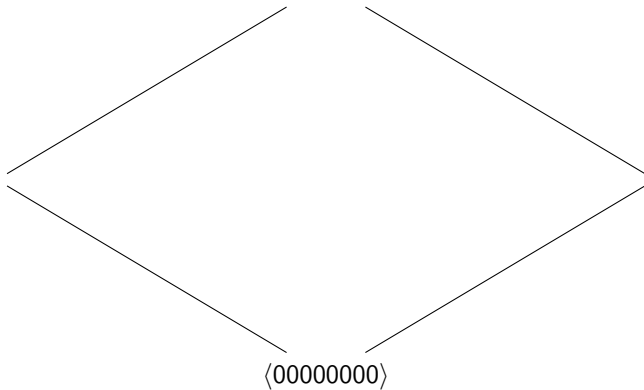
We abstract the parametrisation sets by bounded convex sublattices specified by their infimum and supremum parametrisations (L, U) to obtain the *abstract parametrisation set* $p^\#(T)$.

Abstraction of parametrisation sets



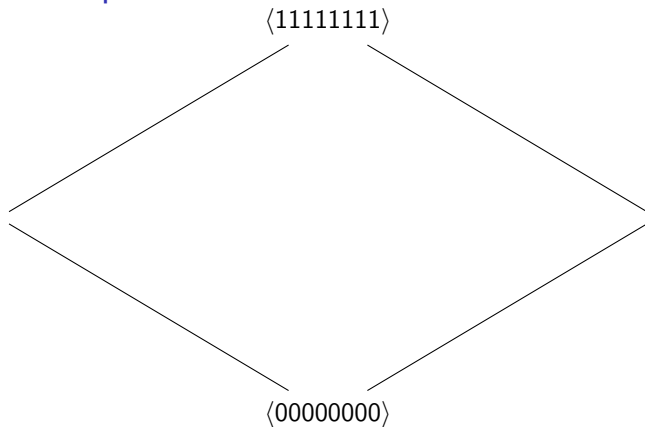
Abstraction of parametrisation sets

$\langle 11111111 \rangle$



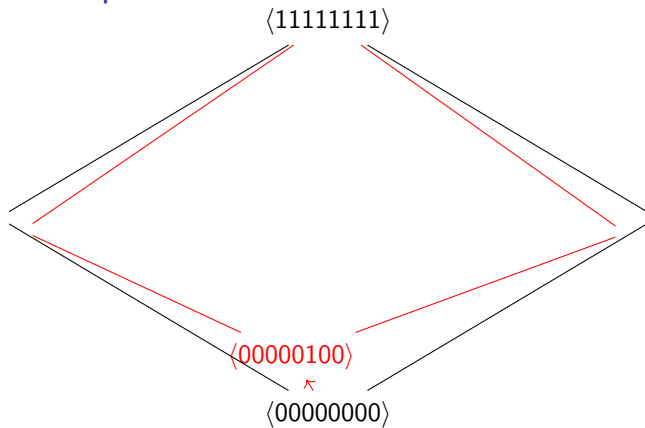
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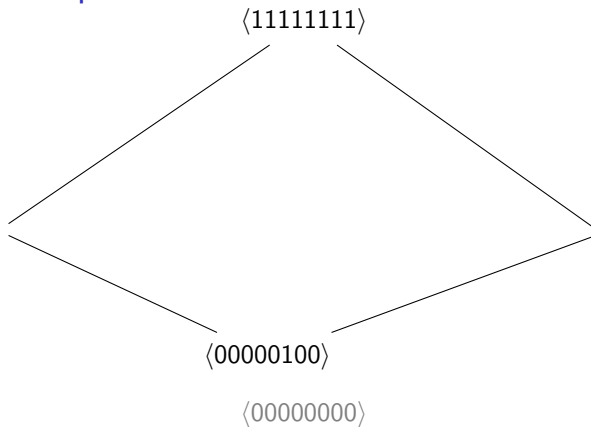
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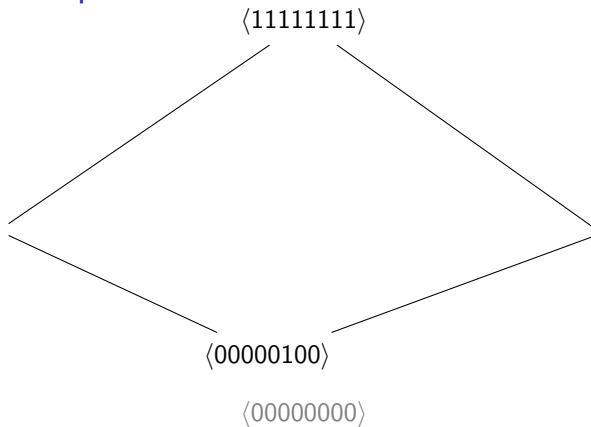
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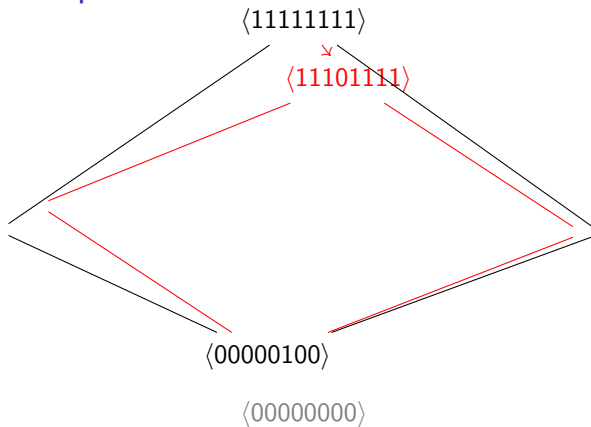
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Abstraction of parametrisation sets



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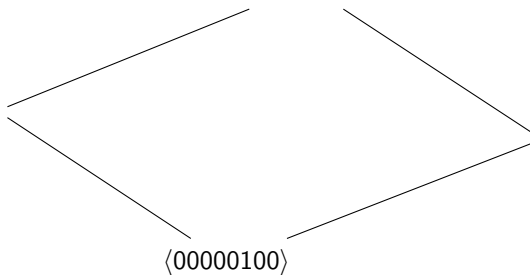


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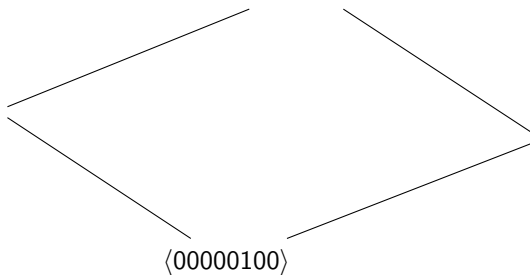
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We compute $p^\#(T \cup \{t\})$ from $p^\#(T)$ in $\mathcal{O}(1)$.

Properties of Parametrisation Set Abstraction

The abstract parametrisation set is equal to the concrete parametrisation set, $p^\#(T) = p(T)$.

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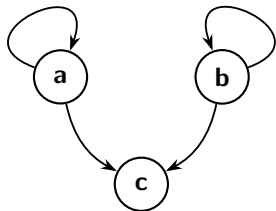
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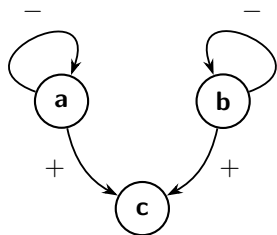
The traces, and in turn, reachable states in the abstract domain are identical to the traces and reachable states in the concrete domain.

Influence Constraints



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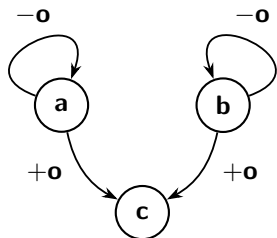
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$(u, v) \in I$ is *positive-monotonic*: $\forall \omega_u < \omega'_u \Rightarrow P_{v,\omega} \leq P_{v,\omega'}$

$(u, v) \in I$ is *negative-monotonic*: $\forall \omega_u < \omega'_u \Rightarrow P_{v,\omega} \geq P_{v,\omega'}$

$(\forall w \in V : w \neq u \Rightarrow \omega_w = \omega'_w)$

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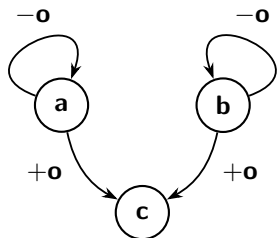
$(u, v) \in I$ is *positive-monotonic*: $\forall \omega_u < \omega'_u \Rightarrow P_{v,\omega} \leq P_{v,\omega'}$

$(u, v) \in I$ is *negative-monotonic*: $\forall \omega_u < \omega'_u \Rightarrow P_{v,\omega} \geq P_{v,\omega'}$

$(u, v) \in I$ is *observable*: $\exists \omega_u \neq \omega'_u \Rightarrow P_{v,\omega} \neq P_{v,\omega'}$

$(\forall w \in V : w \neq u \Rightarrow \omega_w = \omega'_w)$

Influence Constraints



$a = 0$	$P_{a,0} = 1$
$a = 1$	$P_{a,1} = 0$
$b = 0$	$P_{b,0} = 1$
$b = 1$	$P_{b,1} = 0$
$a = 0, b = 0$	$P_{c,00} = 0$
$a = 0, b = 1$	$P_{c,01}$
$a = 1, b = 0$	$P_{c,10}$
$a = 1, b = 1$	$P_{c,11} = 1$

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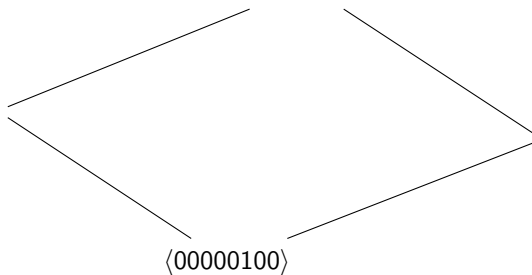
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Abstraction of parametrisation sets

$\langle 11111111 \rangle$

$\langle 11101111 \rangle$



$\langle 00000000 \rangle$

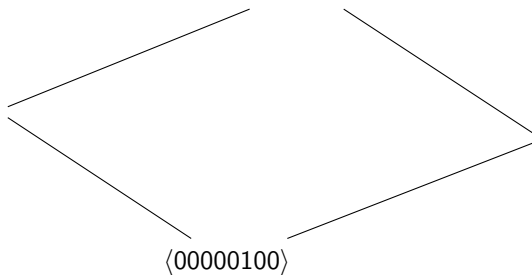
$\langle 010 \rangle \xrightarrow{c,+} \langle 011 \rangle \xrightarrow{b,-} \langle 001 \rangle$

$R = \{(a \xrightarrow{+} c), (b \xrightarrow{o} b)\}$

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$\langle 11101111 \rangle$



$\langle 00000000 \rangle$

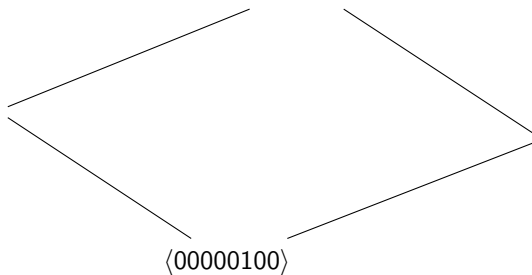
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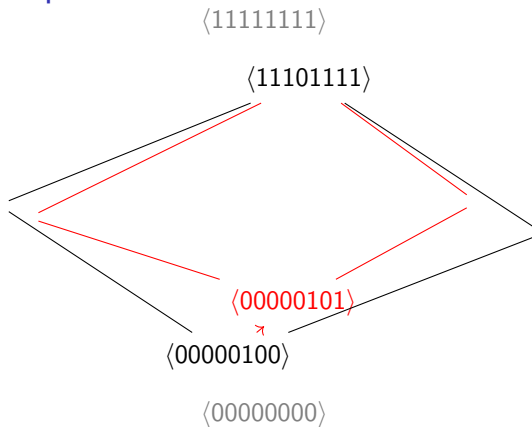
$\langle 00000000 \rangle$

$\langle 010 \rangle \xrightarrow{c,+} \langle 011 \rangle \xrightarrow{b,-} \langle 001 \rangle$

$R = \{(a \xrightarrow{+} c), (b \xrightarrow{o} b)\}$

$P_{c,11} \geq P_{c,01}$

Abstraction of parametrisation sets



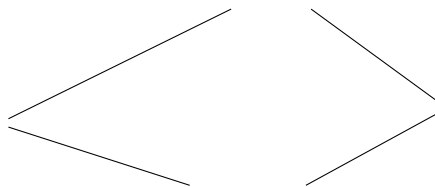
$$\langle 010 \rangle \xrightarrow{c,+} \langle 011 \rangle \xrightarrow{b,-} \langle 001 \rangle$$

$$R = \{(a \xrightarrow{+} c), (b \xrightarrow{o} b)\}$$

Abstraction of parametrisation sets

$\langle 11111111 \rangle$

$\langle 11101111 \rangle$



$\langle 00000101 \rangle$

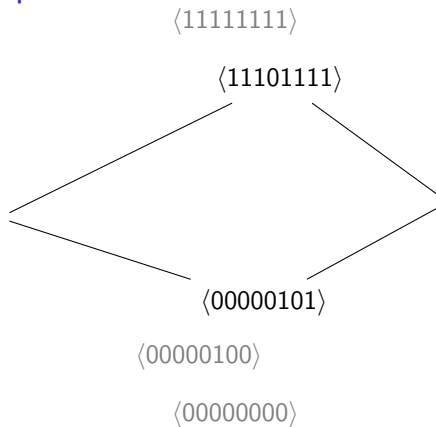
$\langle 00000100 \rangle$

$\langle 00000000 \rangle$

$\langle 010 \rangle \xrightarrow{c,+} \langle 011 \rangle \xrightarrow{b,-} \langle 001 \rangle$

$R = \{(a \xrightarrow{+} c), (b \xrightarrow{o} b)\}$

Abstraction of parametrisation sets

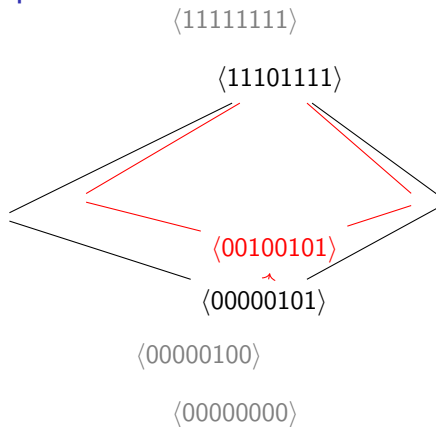


$$\langle 010 \rangle \xrightarrow{c,+} \langle 011 \rangle \xrightarrow{b,-} \langle 001 \rangle$$

$$R = \{(a \xrightarrow{+} c), (b \xrightarrow{o} b)\}$$

$$P_{b,0} \neq P_{b,1}$$

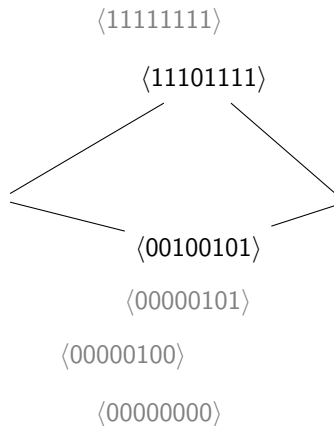
Abstraction of parametrisation sets



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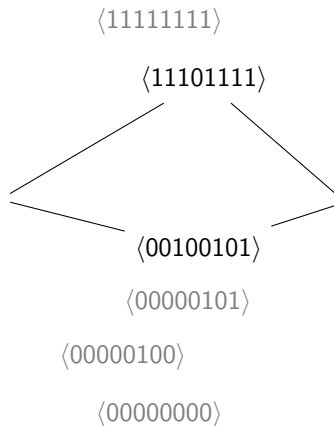
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Abstraction of parametrisation sets



$$\langle 010 \rangle \xrightarrow{c,+} \langle 011 \rangle \xrightarrow{b,-} \langle 001 \rangle$$

$$R = \{(a \xrightarrow{+} c), (b \xrightarrow{o} b)\}$$

We compute $p_R^\#(T \cup \{t\})$ from $p_R^\#(T)$ in $\mathcal{O}(|\Omega_v|)$.

Properties of Parametrisation Set Abstraction

The abstract parametrisation set is equal to the smallest convex sublattice containing concrete parametrisation set,

$$p_R^\#(T) = [p_R(T)].$$

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$$p_R^\#(T) = [p_R(T)].$$

\implies

The abstract set is empty exactly when the concrete set is empty,

$$p_R^\#(T) = \emptyset \Leftrightarrow p_R(T) = \emptyset.$$

\implies

The traces, and in turn, reachable states in the abstract domain are identical to the traces and reachable states in the concrete domain.

Unfoldings

To combat combinatorial explosion of state space we employ **unfolding** as understood by Esparza et al., 2002.

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We modify the **cut-off** criterion to use the subset ordering on parametrisation sets instead of the **total adequate order**.

This leads to 'backwards' **cut-offs**.

We compare against the size of the complete symbolic execution tree achieved from the same initial state by methods of Gallet et al., 2014.

Model	Type	# nodes	# events (incl. cut-offs)	Sym. exec. size
CD ¹ (Fgf8=0)	BN	5	554 (1,939)	8,312
CD (Fgf8=1)	BN	5	1,054 (3,530)	8,312
EGF-TNF α ²	BN	13	1,057 (2,658)	534,498
λ -switch ³	MN	4	170 (575)	68,011
λ -switch (MM)	MN	4	157 (527)	15,139
PSD ⁴ (MM)	MN	14	19,954 (88,994)	-
DS ⁵	MN	15	781 (2,698)	-
DS (MM)	MN	15	731 (2,507)	-

¹Mammalian Cortical Area Development (Giacomantonio et al. 2010)

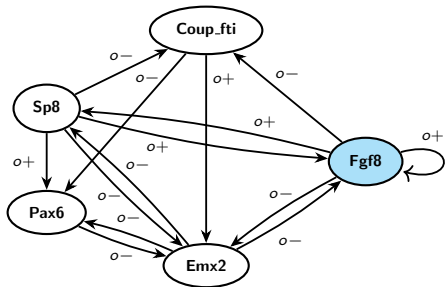
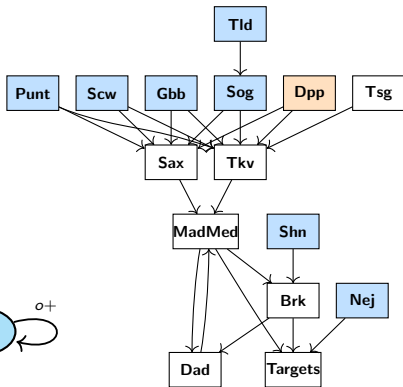
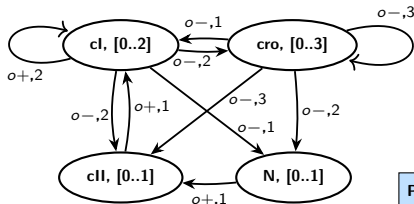
²EGF-TNF α Signalling Pathway (MacNamara et al. 2012), (Ostrowski et al. 2016)

³Regulatory Network of Bacteriophage λ (Gallet et al. 2014), (Klarner et al. 2012)

⁴Primary Sex Determination of Placental Mammals (Sánchez et al. 2016)

⁵Drosophila Signalling (Mbodj et al. 2013)

Examples of Used Networks



Conclusion

Summary:

- ▶ A tight **abstraction of parametrisation sets** using convex sublattices **preserving the reachable state space**.
- ▶ **Unfolding** semantics for Parametric Regulatory Networks utilising the parametrisation set abstraction.
- ▶ Efficient **reachability analysis** of Parametric Regulatory Networks.

Future Work:

- ▶ Attractors of Parametric Regulatory Networks.
- ▶ Explore more fine-grained abstractions.
- ▶ Exploit concurrency even more (contextual unfolding).